

**CAT Coalition  
Policy, Legislative, and Regulatory  
Working Group  
Webinar**

February 13, 2020

# Welcome and Agenda Review

**2:05 Research on AV Legislation**

Bill Covington, University of Washington School of Law

**2:35 Plain Language for ADS Policies and Legislation**

Jennifer Toth, MCDOT & Paul Ajegba, MDOT

**2:50 Quick Update from Focus Area WG – Strategic Initiatives WG**

**2:55 Partner Reports: USDOT, ITS America, ITE, Other**

USDOT – TBD

AASHTO

ITS America

ITE

**3:15 Status of the 5.9 GHz Spectrum**

Pat Zelinski, AASHTO

**3:30 Next Webinar / Close**



# Agenda Item #1: Research on AV Legislation

Bill Covington, University of Washington School of Law

Bill Covington's Slide Show is available at:

[https://docs.google.com/presentation/d/1CTW-tMOTR8CgSmf0s3U1rnG\\_DUdi2ZcodqD6YqxtUP4/edit?usp=sharing](https://docs.google.com/presentation/d/1CTW-tMOTR8CgSmf0s3U1rnG_DUdi2ZcodqD6YqxtUP4/edit?usp=sharing)

# Agenda Item #2: Plain Language for ADS Policies & Legislation

Jennifer Toth and Paul Ajegba

# CAT Terminology – Plain Language for Automated Driving Systems (ADS) Policies

## *The Challenge/Need:*

- Legislators need clear concise nomenclature with common definitions when creating & reviewing policies & legislature

## *The Concept:*

- Review what language & terms are used in existing ADS policies & legislature in member states
- Synthesize terms; identify conflicts, challenges, and commonalities
- Coordinate with a parallel USDOT effort underway
- This effort **Will NOT** create any guidelines or recommendations for nomenclature

# Findings to Date

## ***States Are Mostly Consistent in the Use of Four Key Terms:***

- Terms defined by SAE J3016 Taxonomy Document; re-enforced by AV 3.0
- Generally all terms are consistently defined in states' legislations
- Some states excluded 1 or 2 of the terms

***The states differ in authoritative statements – i.e. how their laws describe the use of automated driving systems***

Four Key Terms Explored:

- Automated Driving Systems
- Dynamic Driving Task
- Minimal Risk Conditions
- Operational Design Domain

# Examples of Different Terms in Authoritative Statements

- Example A: A **driverless-capable vehicle** may operate on the public roads of this state without a conventional human driver physically present in the vehicle, as long as the vehicle meets the following condition
- Example B: Testing or operation of vehicles on public roads that do not have a person present in the vehicle shall be allowed only if such vehicles are **fully autonomous**
- Example C: An **autonomous vehicle** or a **fully autonomous vehicle** may be operated in this state under an autonomous vehicle pilot program approved by the State Highway Commission
- Example D: A person may use an **Automated Driving System** to drive a motor vehicle or to control a function of a motor vehicle if the system is capable of complying with every state and federal law that applies to the function that the system is operating.
- Example E: Notwithstanding any other law, a licensed human operator is not required to operate a **fully autonomous vehicle** .... “A **fully autonomous vehicle** may operate in this state regardless of whether a human operator is physically present in the vehicle.



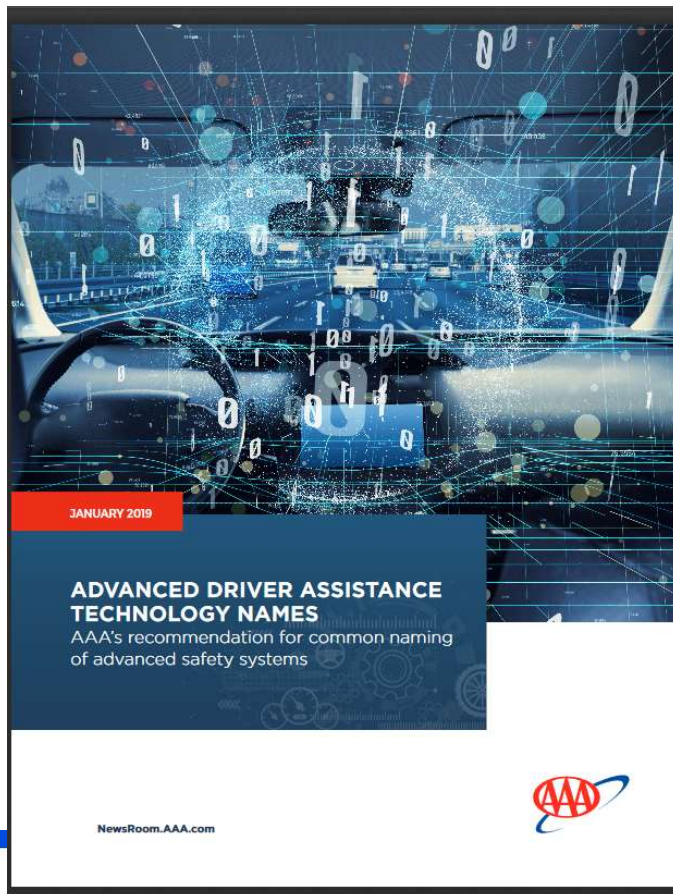
# Examples of Different Terms in Authoritative Statements

- Example F: An **autonomous vehicle** may operate on a public roadway; provided, that the vehicle: <full list omitted>
- Example G: A person may operate a **fully autonomous vehicle with the automated driving system engaged** without a human driver being present in the vehicle, provided that such vehicle: <full list omitted>
- Example H: An **autonomous vehicle** may be operated on public roads for testing purposes by a driver who possesses the proper class of license for the type of vehicle being operated if all of the following requirements are met
- Example I: An **autonomous vehicle with automated driving systems** engaged does not require a human driver to operate on the public highway if the autonomous vehicle is capable of achieving a minimal risk condition in case a system failure occurs which renders the automated driving system unable to perform the entire dynamic driving task relevant to the vehicle's intended operational design domain.

# Summary of Findings

Terms in Authority Statement	# of states reviewed – use this term for the Authority Statement
Autonomous Vehicle	3
Fully Autonomous Vehicle	2
Driverless capable vehicle	2
Fully autonomous (“...if such vehicles are fully autonomous”)	1
Automated driving system	1
Autonomous vehicle with automated driving systems engaged	1
Fully autonomous vehicle with automated driving systems engaged	1

# AAA Recommendations for ADAS Technology



<https://www.aaa.com/AAA/common/AAR/files/ADAS-Technology-Names-Research-Report.pdf>

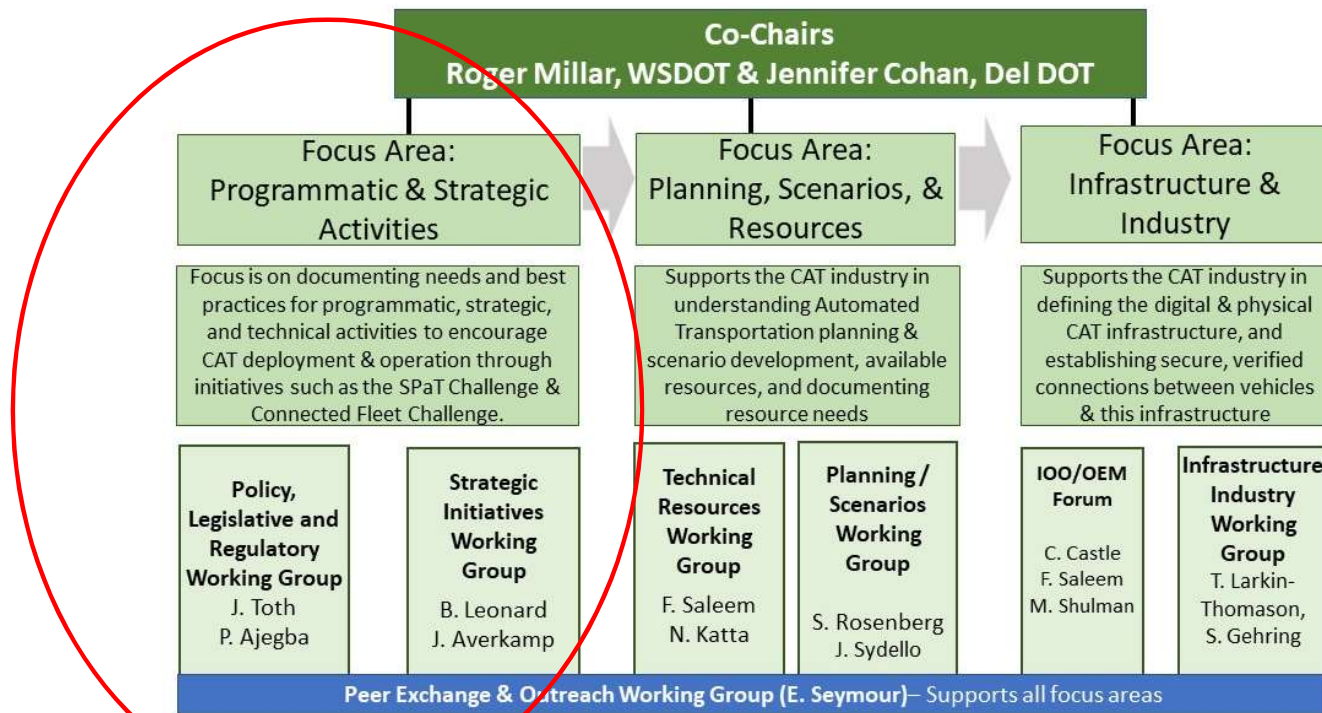
# Discussion

- Is this topic appropriate for an NCHRP Problem Statement?
- Should this working group pursue this topic further?

# **Agenda Item #3: Brief Update from the Focus Area Working Group: Strategic Initiatives WG**

Blaine Leonard, Utah DOT & Chair of Strategic Initiatives WG

# Programmatic & Strategic Activities Focus Area



# Strategic Initiatives WG – Jan. 23<sup>rd</sup> Webinar

## Three presentations:

- Example of a Connected Fleet Vehicle deployed to broadcast Basic Safety Message;
  - Maryland Transportation Authority
- Two Projects that Tested Latency of DSRC vs. 4G LTE:
  - New Hampshire DOT / City of Dover
  - Caltrans / PATH

# Strategic Initiatives WG – Other Activities

## Survey of SPaT Challenge sites to understand approaches to security credentialing (SCMS):

- Early input:
  - 7 States responded:
    - ❖ 6 are pursuing SCMS to secure broadcasts
      - 4 with Greenhill / ISS
      - 1 with BlackBerry
      - 1 researching both Greenhill/ISS and BlackBerry
    - ❖ 1 State is not pursuing security at this time (demonstration project)



# Strategic Initiatives WG – Other Activities

## Enabling Connected Intersections:

- Majority of SPaT/MAP broadcasts are received by fleet vehicles (e.g. transit, snowplows) or after-market On-board units
- At least one formal announcement from an OEM has stated that production vehicles will have on-board safety applications starting in 2022
- Outside of the communications uncertainties that exist, there are data related actions needed to “enable” this connectivity to production vehicles

# Strategic Initiatives WG – Other Activities

## Enabling Connected Intersections – activities include:

- Agreeing to Minimum Requirements (update to the SPaT Challenge ConOps & Requirements)
- Final Test Plan & Verification Process
- Deployment Tracking Approach
- O&M Approach
- Security Requirements

***Goal is to ensure OEMs trust IOO data for production applications***

# Agenda Item #4: Partner Reports

USDOT

AASHTO

ITE

ITS America



# Agenda Item #5: Update on the Status of the 5.9 GHz Spectrum

Pat Zelinski, AASHTO

All

# Other Member Updates

(If time allows)

# Upcoming CAT PLR WG Webinars

- April 2, 2020 (11:00 am ET)
  - Maas/MOD Presenters needed
- **Potential future presentation:**
  - **Uniform Law Commission “Uniform Automated Operation of Vehicles Act”**

**Any Other Business / Adjourn**